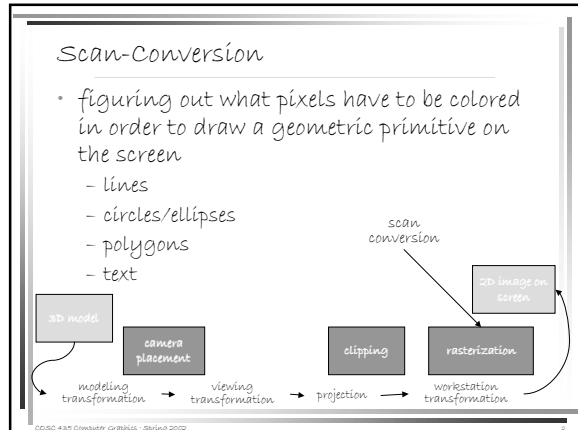


Scan-Conversion



- ## Scan-Conversion Overview
- lines
 - DDA
 - midpoint/Bresenham
 - circles
 - midpoint circle
 - filled polygons
 - scan-line
 - antialiasing

Scan-Conversion: Lines

the task: draw a line on a raster screen between two points

- mathematical line vs. rasterized line
 - jaggies

revised task: given two integer-coordinate points on the plane, determine what pixels on a raster screen should be on to create a picture of a unit-width line segment between those points

A Simplification

- we'll consider only lines with slope $0 < m < 1$
 - horizontal and vertical lines are special cases
 - diagonal lines ($m = \pm 1$) can be special-cased or included in general case
 - can use symmetry to adapt solution for $0 < m < 1$ for $m > 1$ and negative slopes

Another Simplification

- consider line with slope $0 < m < 1$
 - generally only one pixel per column inside the unit-width line segment
 - we'll draw just one pixel per column, using the closest to the "true line" if there are two choices
 - vertical distance from point to line is proportional to perpendicular distance

Lines: Basic Algorithm

- find the equation of the line connecting endpoints P & Q
- starting with the leftmost point P , $x_i = x_{i-1} + 1$ and $y_i = m \cdot x_i + b$
- color pixel at $(x_i, \text{round}(y_i))$
- each iteration requires floating-point multiplication

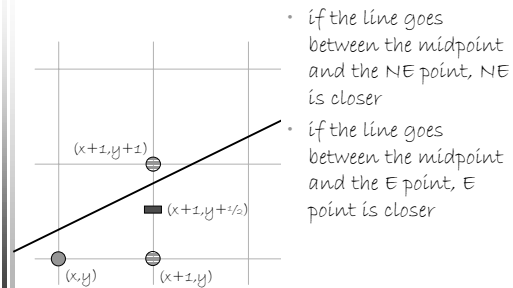
Lines: DDA Algorithm

- determine slope of the line connecting endpoints P & Q
- starting with the leftmost point P , $x_i = x_{i-1} + 1$ and $y_i = y_{i-1} + m$
- color pixel at $(x_i, \text{round}(y_i))$
- each iteration still requires floating-point arithmetic and rounding
- repeated summing of fractional values can lead to roundoff problems for very long lines

Lines: Midpoint Line Algorithm

- observation: the next pixel colored is always either E or NE of the current pixel
- need a way to decide between the choices...
 - (and with only using integer arithmetic)
- let's consider the midpoint between the two choices...

The Midpoint



Equation of a Line

- one way to express a line
 - $y = mx + B = (\Delta y / \Delta x)x + B$
 - m is the slope, B is the y intercept
- another way of expressing a line
 - $F(x, y) = ax + by + c = 0$
 - rearranging the first equation yields $(\Delta y)x - (\Delta x)y + (\Delta x)B = 0$
 - $F(x, y) = 0$ if (x, y) is on the line
 - $F(x, y) < 0$ if (x, y) is above the line
 - $F(x, y) > 0$ if (x, y) is below the line

Putting the Bits Together

- if midpoint is below the line, then line is between midpoint and NE
 - if $F(x_m, y_m) > 0$, choose NE
- if midpoint is above the line, then line is between midpoint and E
 - if $F(x_m, y_m) < 0$, choose E
- if midpoint is on the line, then line goes through the midpoint
 - if $F(x_m, y_m) = 0$, choose either E or NE (but be consistent)
- we'll write $F(x_m, y_m)$ as d and call it the decision variable

Notation Roundup

- line endpoints are $P=(x_p, y_p)$ and $Q=(x_q, y_q)$
 - $\Delta x = x_q - x_p$, $\Delta y = y_q - y_p$
 - P and Q have integer coordinates
- pixels are colored one column at a time
 - (x_k, y_k) are the coordinates of the pixel colored in column k , $0 \leq k \leq \Delta y$ (k is an integer)
 - $x_{k+1} = x_k + 1$
 - $(x_0, y_0) = P$, $(x_{\Delta y}, y_{\Delta y}) = Q$
 - $d_k = F(x_{k-1} + 1, y_{k-1} + 1/2)$
 - d_k is decision variable used to choose where pixel in column k goes

An Algorithm Based on the Midpoint

- to compute $(x_{k+1}, y_{k+1}) \dots$
 - midpoint is $(x_k + 1, y_k + 1/2)$
 - compute $d_{k+1} = F(x_k + 1, y_k + 1/2)$
 - $x_{k+1} = x_k + 1$
 - if $d_{k+1} > 0$, $y_{k+1} = y_k + 1$
 - otherwise, $y_{k+1} = y_k$
- this works, but computing $F(x_k + 1, y_k + 1/2)$ involves several floating-point additions & multiplications
 - we're trying to eliminate floating point!

Making It Incremental

- if $d_{k+1} = d_k + \Delta$ we could save work

$$d_{k+1} - d_k = F(x_k + 1, y_k + 1/2) - F(x_{k-1} + 1, y_{k-1} + 1/2)$$

$$= (\Delta y)(x_k + 1) - (\Delta x)(y_k + 1/2) + (\Delta x)E - [(\Delta y)(x_{k-1} + 1) - (\Delta x)(y_{k-1} + 1/2) + (\Delta x)E]$$

$$= (\Delta y)(x_k - x_{k-1}) - (\Delta x)(y_k - y_{k-1})$$

$$= (\Delta y)(x_{k-1} + 1 - x_{k-1}) - (\Delta x)(y_k - y_{k-1})$$

$$= \Delta y - \Delta x (y_k - y_{k-1}) = \Delta$$
- relationship between y_k and y_{k-1} depends on whether we chose NE or E pixel for (x_k, y_k)

Making It Incremental

- $$d_{k+1} - d_k = \Delta y - (\Delta x)(y_k - y_{k-1})$$
- relationship between y_k and y_{k-1} depends on whether we chose NE or E pixel for (x_k, y_k)
 - if E... $y_k = y_{k-1}$

$$d_{k+1} - d_k = \Delta y = \Delta_E$$
 - if NE... $y_k = y_{k-1} + 1$

$$d_{k+1} - d_k = \Delta y - (\Delta x)(y_{k-1} + 1 - y_{k-1})$$

$$= \Delta y - \Delta x = \Delta_{NE}$$
 - Δ_E and Δ_{NE} are constants...

The Incremental Approach

- to compute $(x_{k+1}, y_{k+1}) \dots$
 - assume d_{k+1} has already been computed
 - $x_{k+1} = x_k + 1$
 - if $d_{k+1} > 0$, $y_{k+1} = y_k + 1$ and $d_{k+2} = d_{k+1} + \Delta_{NE}$
 - otherwise, $y_{k+1} = y_k$ and $d_{k+2} = d_{k+1} + \Delta_E$

Initial values

- but what are x_0, y_0, d_1 ?
 - x_0 and y_0 are the coordinates of the lower left endpoint

$$d_1 = F(x_0 + 1, y_0 + 1/2)$$

$$= (\Delta y)(x_0 + 1) - (\Delta x)(y_0 + 1/2) + (\Delta x)E$$

$$= (\Delta y)x_0 - (\Delta x)y_0 + (\Delta x)E + \Delta y - \Delta x/2$$

$$= F(x_0, y_0) + \Delta y - \Delta x/2$$
 - (x_0, y_0) is an endpoint and thus on the line, so $F(x_0, y_0) = 0$

$$d_1 = \Delta y - \Delta x/2$$
 - but $\Delta x/2$ may not be integer!

Making It Integer

$$d_i = \Delta y - \Delta x / 2$$

- d_i may not be integer
 - so, multiply by 2! (Δy and Δx are integers)
 - this doesn't affect the sign of d , which is all that matters
- we now use $d_{k+1} = 2 \cdot F(x_k + 1, y_k + 1/2)$
 - so $d_i = 2\Delta y - \Delta x$
 - this also means that Δ_E and Δ_{NE} are twice as big: $\Delta_E = 2\Delta y$ and $\Delta_{NE} = 2\Delta y - 2\Delta x$

$0 < m < 1$ Midpoint Line Algorithm

- compute $2\Delta x$, $2\Delta y$, and $2\Delta y - 2\Delta x$
- initialize (x, y) to the lower leftmost point and $d = 2\Delta y - \Delta x$
- color pixel (x, y)
- repeat...
 - increment x
 - if $d > 0$, increment y and add $\Delta_{NE} = 2\Delta y - 2\Delta x$ to d
 - otherwise, add $\Delta_E = 2\Delta y$ to d
 - color pixel (x, y)

Midpoint Line Summary

- algorithm is integer & incremental (for speed)
- simplifications
 - one pixel per column (a hack to make it easier)
 - only consider $0 < m < 1$ (other cases by symmetry)
- key observation: given pixel colored in column k , next pixel is either E or NE
 - need a decision variable to use to make choice

Midpoint Line Summary #2

- decision variable
 - use sign (+, -, 0) to make choice
 - the sign of $F(x, y)$ tells which side of the line point (x, y) is on
 - determine what side of line midpoint is on
 - if line is between midpoint and E, E is closer to line i.e. choose E if $F(x_m, y_m) < 0$
 - ditto for NE i.e. choose NE if $F(x_m, y_m) > 0$
- making it integer & incremental
 - use $2F(x, y)$ as decision var instead of $F(x, y)$
 - don't recompute $F(x, y)$ each time - instead, increment previous value by some amount